

III Semester M.Sc. Degree Examination, December 2015  
 (Y2K11 (RNS) Scheme)  
 MATHEMATICS  
 M 303 : Differential Geometry

Time : 3 Hours

Max. Marks : 80

*Instructions :* 1) Answer any five questions, choosing atleast two from each Part.  
 2) All questions carry equal marks.

## PART - A

1. a) Define directional derivatives of a real valued differentiable function on  $E^3$

If  $V_p = (v_1, v_2, v_3)_p$  is a tangent vector to  $E^3$  at  $P$  and  $f$  is any real valued differentiable function on  $E^3$ , then prove that the  $V_p[f] = \sum_{i=1}^3 v_i \frac{\partial f}{\partial x_i}(P)$ . Further

compute  $V_p[f]$  for  $f = y/z$  for give  $V = (2, -1, 3)$ ,  $P = (2, 0, -1)$  9

b) Show that every regular curve on  $E^3$  has a unit speed reparametrization

Find unit speed reparametrization of the curve  $\alpha(t) = (\cosh t, \sinh t, t)$  7

2. a) Compute the derivative  $df$  of  $f = xy^2 - yz^2$  and evaluate  $df$  on  $V_p[f]$ , where

$V = (1, 2, -3)$ ,  $P = (0, -2, 1)$ . 4

b) Let  $\phi = xdx - ydy$  and  $\theta = zdy$ . Then find  $\phi \wedge \theta$ , verify the formula

$d(\phi \wedge \theta) = d\phi \wedge \theta - \phi \wedge d\theta$ . 5

c) Let  $F : E^3 \rightarrow E^3 : F = (f_1, f_2, f_3)$  be a mapping. Prove that for any tangent vector  $V_p$  to  $E^3$  at  $P$ ,

$F_{*p}(V_p) = (V_p[f_1], V_p[f_2], V_p[f_3])$  and deduce that  $F_{*p}$  is linear. Further compute

$F_{*p} V_p$  for  $F(x, y, z) = (x, xy, xyz)$  and  $V = (1, -1, 3)$ ,  $P = (2, 1, 0)$ . 7



3. a) Derive Frenet-formula for a unit speed curve. 5
- b) Let  $\beta$  be a unit speed curve with curvature  $K > 0$ . Show that if the torsion  $\tau$  of  $\beta$  is zero, then  $\beta$  is part of a circle of radius  $\frac{1}{K}$ . 5
- c) With usual notations prove
- $\nabla_{\mathbf{v}_i} W = \sum V_{ij}(W)U_j(P)$ ,  $W = (w_1, w_2, w_3)$ ,  $\nabla_{\mathbf{v}_i} W$  of the vector field
- $W = xU_1 + x^2U_2 - x^3U_3$  with respect to the tangent vector  $\mathbf{V}_i$ ,  $\mathbf{V}_i = (1, -1, 2)$ ,  $P = (1, 3, -1)$ . 6

4. a) Compute the connection forms of the frame field

$$E_1 = \frac{1}{\sqrt{2}} (\sin t U_1 + U_2 - \cos t U_3)$$

$$E_2 = \frac{1}{\sqrt{2}} (\sin t U_1 - U_2 - \cos t U_3)$$

$$E_3 = \cos t U_1 + \sin t U_2, \text{ for a function } t.$$

- b) Verify Cartan's structural equations for cylindrical frame field. 5
- c) Let  $F: E^3 \rightarrow E^3$  be an isometry. Prove that there is a unique transformation  $T$  and a unique orthogonal transformation  $C$ , such that  $F = TC$ . 6

#### PART - B

5. a) Define a surface in  $E^3$ . Using the definition show that a unit sphere in  $E^3$  is a surface in  $E^3$ . 5
- b) If  $f$  is any real valued differentiable function on an open set  $D$  in  $E^3$ . Then show that the function  $X: D \rightarrow E^3$
- $$X(u, v) = (u, v, f(u, v)), \quad \forall u, v \in D \subset E^3 \text{ is a proper patch in } E^3$$
- 5
- c) Let  $g$  be any real valued differentiable function on  $E^3$  and  $C$  be a real number. Show that the set  $M = \{(x, y, z) \in E^3 / g(x, y, z) = C\}$  is a surface in  $E^3$  if  $dg \neq 0$  at any point of  $M$ . 6
6. a) Let  $M = \{(x, y, z) \in E^3 / g(x, y, z) = C\}$  be a surface in  $E^3$ . Prove that the gradient  $\nabla g$  is a non-vanishing normal vector field on  $M$ . 8
- b) Define pull back of a differential form. Show that if  $X: D \subset E^2 \rightarrow M$  is a patch and  $\phi$  and  $\gamma$  are respectively 1-form and 2-form on  $M$ , then
- i)  $X^*(\phi) = \phi(X_i)du + \phi(X_j)dv$       ii)  $X^*(\gamma) = \gamma(X_i, X_j) du dv$ . 8

- 7 a) If  $P$  is a umbilic point of a surface  $M$  in  $\mathbb{E}^3$ , then prove that shape operator  $S$  of  $M$  is just a scalar multiple by  $K = K_1 = K_2$ . Further prove that if  $P$  is non-umbilic then there are exactly two principal directions which are orthogonal.

8

- b) Prove that the Gaussian and mean curvature of surface are given by

$$K = \frac{\begin{vmatrix} s_v \cdot v & s_v \cdot w \\ s_w \cdot v & s_w \cdot w \end{vmatrix}}{\begin{vmatrix} v \cdot v & v \cdot w \\ w \cdot v & w \cdot w \end{vmatrix}}$$

$$H = \frac{\begin{vmatrix} s_v \cdot v & s_v \cdot w \\ w \cdot v & w \cdot w \end{vmatrix} + \begin{vmatrix} v \cdot v & v \cdot w \\ s_w \cdot v & s_w \cdot w \end{vmatrix}}{2 \begin{vmatrix} v \cdot v & v \cdot w \\ w \cdot v & w \cdot w \end{vmatrix}}$$

8

8. a) Compute the Gaussian and mean curvature of

i)  $X(u, v) = (u \cos v, u \sin v, bv)$ ,  $b \neq 0$

ii) Saddle surface  $z = xy$ .

9

- b) Compute the geodesics of (i) sphere (ii) cylinder

7